

An introduction to fixed parameter tractability and kernelization

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On the topic

- Fixed parameter tractability: recent direction in algorithm research
- Kernelization: offspring – allows mathematical analysis of preprocessing for problems
- This talk: informal introduction to central notions
 - Simple examples
 - Some definitions, proofs, algorithms
 - Not much “uncertainty” / ECSQARU problems discussed in this talk...



Schedule

1. Fixed parameter tractability
2. Hardness
3. Kernelization
4. Kernel lower bounds
5. Conclusions



1

Introduction

Parameterized complexity:

What is it about



Fixed Parameter Complexity

- Many problems have a *parameter*
- Many applications have this parameter to be *small*
 - E.g.: facility location with small number of facilities (place k hospitals on a large map)
 - Structural parameter of input that is likely to be small
- Sometimes, faster / better algorithms are possible



Parameterized problem

- Problem with two argument input:
 - **Given:** Some information x , integer k , ...
 - **Parameter:** k
 - **Question:** $Q(x, k)$?
- Many examples ...



Examples of parameterized problems (1)

Graph Coloring

Given: Graph G , integer k

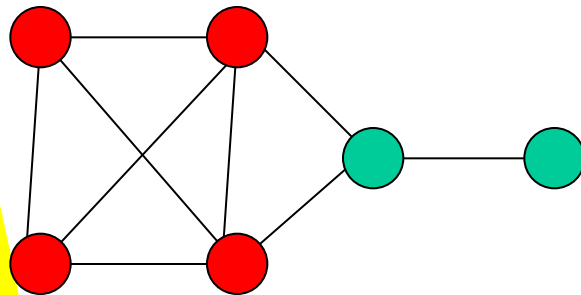
Parameter: k

Question: Is there a vertex coloring of G with k colors? (I.e., $c: V \rightarrow \{1, 2, \dots, k\}$ with for all $\{v, w\} \in E: c(v) \neq c(w)$?)

- **NP-complete, even when $k=3$.**

Clique

- Subset W of the vertices in a graph, such that each pair has an edge



Examples of parameterized problems (2)

Clique

Given: Graph G , integer k

Parameter: k

Question: Is there a clique in G of size at least k ?

- Solvable in $O(n^k)$ time with simple algorithm. Complicated algorithm gives $O(n^{2k/3})$. Seems to require $\Omega(n^{f(k)})$ time...

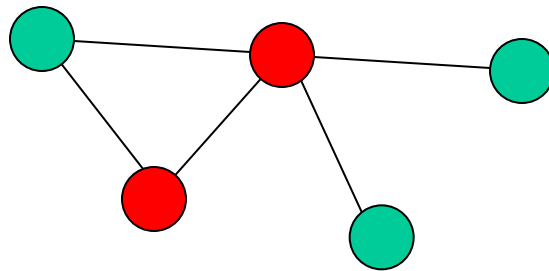


Simple $O(n^k)$ algorithm

- More or less like this:
 - For each set S of k vertices in G :
 - If S is a clique, then return yes
 - (If none returned yes:) return no
- ... hardly anything better known ...

Vertex cover

- Set of vertices $W \subseteq V$ with for all $\{x,y\} \in E$: $x \in W$ or $y \in W$.
- **Vertex Cover** problem:
 - Given G , find vertex cover of minimum size



Examples of parameterized problems (3)

Vertex cover

Given: Graph G , integer k

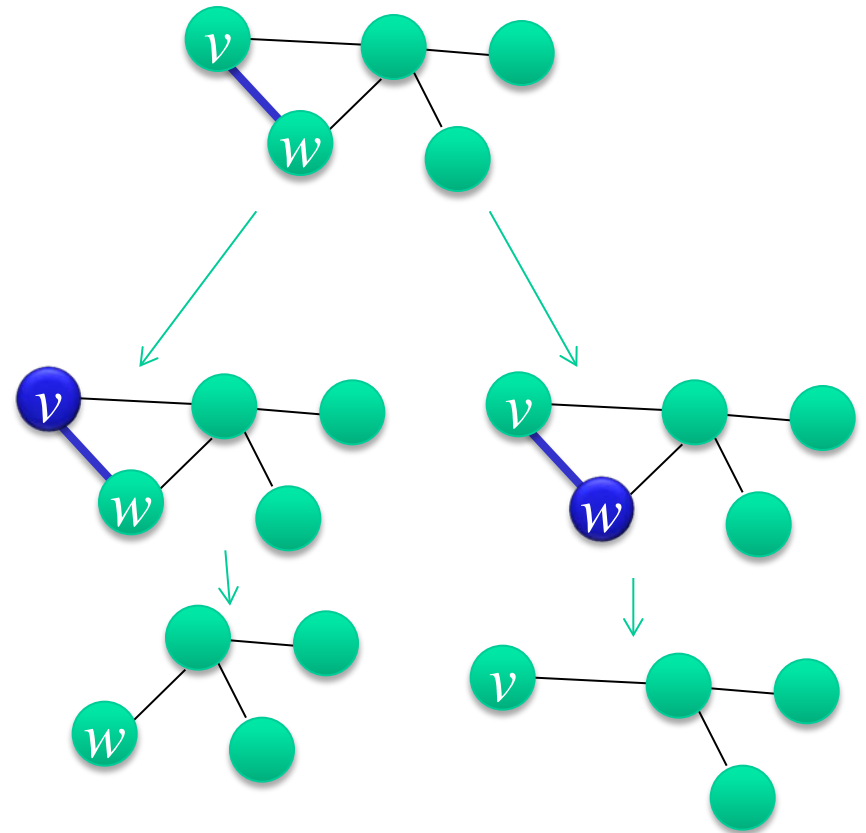
Parameter: k

Question: Is there a vertex cover of G of size at most k ?

- Solvable in $O(2^k (n+m))$ time

Idea for algorithm

- Take an edge $\{v, w\}$
- In each solution S , we have v or w (or both)
- If we take v , then this is similar to looking at the graph obtained by removing v and all its edges



Vertex Cover in $O(2^k (n+m))$ time

- Recursive algorithm
- $VC(G, k)$
 - If G has no edges: return yes
 - If $k == 0$: return no
 - Choose an edge $e = \{v, w\}$
 - Let G' be obtained from G by removing v and all its edges
 - Let G'' be obtained from G by removing w and all its edges
 - Return $VC(G', k-1)$ or $VC(G'', k-1)$



Three types of complexity

- When the parameter is fixed
 - Still NP-complete (k -coloring, take $k=3$)
 - $O(f(k) n^c)$
 - $O(n^{f(k)})$



Fixed parameter complexity theory

- To distinguish between behavior:
 - $O(f(k) * n^c)$
 - $\Omega(n^{f(k)})$
- Proposed by Downey and Fellows.

Parameterized problems

- Instances of the form (x, k)
 - I.e., we have a *second parameter*
- Decision problem (subset of $\{0,1\}^* \times \mathbf{N}$)
- Notation: k is the parameter, n measures size of x



Fixed parameter tractable problems

- **FPT** is the class of problems with an algorithm that solves instances of the form (x, k) in time $p(|x|) \cdot f(k)$, for polynomial p and some function f .
 - E.g. $O(3^k n^2)$, $O(k! n)$, ...



Hard problems

- Complexity classes
 - $W[1] \subseteq W[2] \subseteq \dots W[i] \subseteq \dots W[P]$
 - Defined in terms of *Boolean circuits*
 - Problems **hard** for $W[1]$ or larger class are assumed not to be in FPT
 - Compare with P / NP



Examples of hard problems

- Clique and Independent Set are $W[1]$ -complete
- Dominating Set is $W[2]$ -complete
- Version of Satisfiability is $W[1]$ -complete
 - **Given:** set of clauses, k
 - **Parameter:** k
 - **Question:** can we set (at most) k variables to **true**, and all others to **false**, and make all clauses true?



So what is parameterized complexity about?

- Given a parameterized problem
- Establish that it is **in FPT**
 - And then design an algorithm that is as fast as possible
- *Or* show that it is **hard for $W[1]$** or “higher”
 - Try to find a polynomial time algorithm for fixed parameter
- *Or* even show that it is **NP-complete** for fixed parameters
 - Solve it with different techniques (exact or approximation)

FPT techniques

- Several algorithmic techniques to show that problems are in FPT
 - Branching
 - Dynamic programming
 - Exploiting structures like tree decompositions (clique trees, junction trees); linear structure of problem instances ...
 - Advanced, specialized techniques:
 - Iterative improvement
 - Color coding
 - ...



Closest string

- **Given:** k strings s_1, \dots, s_k each of length L , integer d
- **Parameter:** d
- **Question:** is there a string s with Hamming distance at most d to each of s_1, \dots, s_k
- Application in molecular biology
- Here: FPT algorithm
- (Gramm and Niedermeier, 2002)



Subproblems

- Subproblems have form
 - Candidate string s
 - Additional parameter r
 - We look for a solution to original problem, with additional condition:
 - Hamming distance at most r to s
- Start with $s = s_1$ and $r=d$ (= original problem)



Branching step

- Choose an s_j with Hamming distance $> d$ to s
- If Hamming distance of s_i to s is larger than $d+r$:
NO
- For all positions i where s_j differs from s
 - Solve subproblem with
 - s changed at position i to value s_j (j)
 - $r = r - 1$
- Note: we find a solution, if and only one of these subproblems has a solution



Example

- Strings 01112, 02223, 01221, $d=3$
 - First position in solution will be a 0
 - First subproblem (01112, 3)
 - Creates three subproblems
 - (02113, 2)
 - (01213, 2)
 - (01123, 2)

Time analysis

- Recursion depth d
- At each level, we branch at most at $d + r \leq 2d$ positions
- So, number of recursive steps at most d^{2d+1}
- Each step can be done in polynomial time: $O(kdL)$
- Total time is $O(d^{2d+1} \cdot kdL)$
- Speed up possible by more clever branching and by kernelisation



Technique

- Try to find a branching rule that
 - Decreases the parameter
 - Splits in a bounded number of subcases
 - YES, if and only if YES in at least one subcase



Color coding

- Interesting algorithmic technique to give fast FPT algorithms
- As example:
- **Long Path**
 - **Given:** Graph $G=(V,E)$, integer k
 - **Parameter:** k
 - **Question:** is there a simple path in G with at least k vertices?



Problem on colored graphs

- **Given:** graph $G=(V,E)$, for each vertex v a color in $\{1,2, \dots , k\}$
- **Question:** Is there a simple path in G with k vertices of **different** colors?
 - Note: vertices with the same colors may be adjacent.
- Can be solved in $O(2^k (nm))$ time using dynamic programming
- Used as subroutine...



DP

We skip
this slide

- Tabulate:
 - (S, v) : S is a set of colors, v a vertex, such that there is a path using vertices with colors in S , and ending in v
 - Using **Dynamic Programming**, we can tabulate all such pairs, and thus decide if the requested path exists

A randomized variant

- For each vertex v , *guess a color* in $\{1, 2, \dots, k\}$
- Check if there is a path of length k with only vertices with different colors
- Note:
 - If there is a path of length k , we find one with positive chance ($2^k / k!$)
 - We can do this check in $O(2^k nm)$ time
 - Repeat the check many times to get good probability for finding the path



From randomized to deterministic

- Randomized algorithm:
 - Repeat many times:
 - Guess colors
 - Solve DP; if YES, then return YES
 - Return NO
- Derandomization is possible with *k-perfect family of hash functions* (replacing guesses)...

4

Hardness proofs



Remember Cook/Levin theorem

- NP-completeness helps to distinguish between decision problems for which we have a polynomial time algorithm, and those for which we expect no such algorithm exists
- NP-hard; NP-completeness; reductions
- Cook/Levin theorem: `first' NP-complete problem; used to prove others to be NP-complete
- Similar theory for parameterized problems by Downey and Fellows



Classes

- $\text{FPT} \subseteq \text{W}[1] \subseteq \text{W}[2] \subseteq \text{W}[3] \subseteq \dots \subseteq \text{W}[i] \subseteq \dots \subseteq \text{W}[P]$
- Theoretical reasons to *believe* that hierarchy is strict
- **Theorem:** If $\text{FPT} = \text{W}[1]$, then the Exponential Time Hypothesis does not hold
- ETH (Impagliazzo et al., 1999): There is a δ such that 3-Satisfiability cannot be solved in $O(2^{\delta n})$ time



Scheme

- Define a notion of *reduction*
- From the notion of reduction, we get *hardness* and *completeness*
- Generic hard/complete problems + reduction give new hard/complete problems

Parameterized m -reduction

- Let L, L' be parameterized problems.
- A *standard parameterized m -reduction* transforms an input (I, k) of L to an input $(f(I, k), g(k))$ of L'
 - $L((I, k))$ if and only if $L'((f(I, k), g(k)))$
 - f uses time $p(|I|) \cdot h(k)$ for a polynomial p , and some function h
- Note: time may be exponential or worse in k
- Note: the parameter only depends on parameter, not on rest of the input

A Complete Problem

- Classes $W[1]$, ... are defined in terms of circuits (definition skipped here)
- Short Turing Machine Acceptance
 - Given: A non-deterministic Turing machine M , input x , integer k
 - Parameter: k
 - Question: Does M accept x in a computation with at most k steps?
- Short Turing Machine Acceptance is $W[1]$ -complete (compare Cook)
- Note: easily solvable in $O(n^{k+c})$ time



More complete problems for $W[1]$

- Weighted q -CNF Satisfiability
 - Given: Boolean formula in CNF, such that each clause has at most q literals, integer k
 - Parameter: k
 - Question: Can we satisfy the formula by making at most k literals true?
- For each fixed $q > 1$, Weighted q -CNF Satisfiability is complete for $W[1]$.

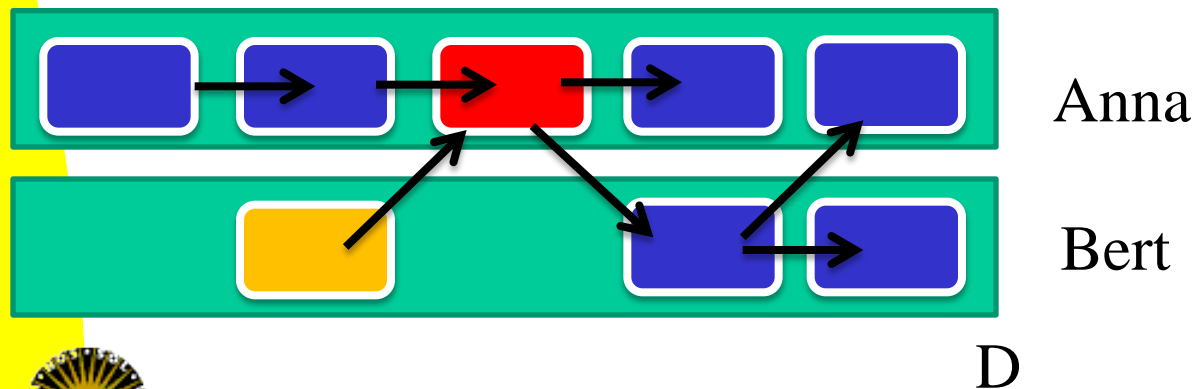
Hard problems

- Independent Set, Clique: $W[1]$ -complete
- Dominating Set: $W[2]$ -complete
- Longest Common Subsequence III: $W[1]$ -complete (complex reduction to Clique)
 - Given: set of k strings S^1, \dots, S^k , integer m
 - Parameter: k, m
 - Question: is there a string S of length m that is a subsequence of each string S^i , $1 \leq i \leq k$?



Example reduction

- K people have to do n tasks. Each task costs 1 hour. Some tasks have to be done before some other tasks, and there is a deadline D .
- Can we finish all tasks before D ?



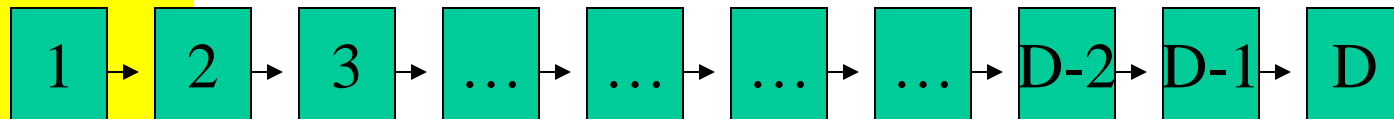
Formal problem

- Precedence constrained K -processor scheduling
 - Instance: set of tasks T , each taking 1 unit of time, partial order $<$ on tasks, deadline D , number of people that can carry out tasks K
 - Parameter: K
 - Question: can we carry out the tasks by K people, such that
 - If $\text{task1} < \text{task2}$, then task1 is carried out before task2
 - At most one task per time step per person
 - All tasks finished at most at time D



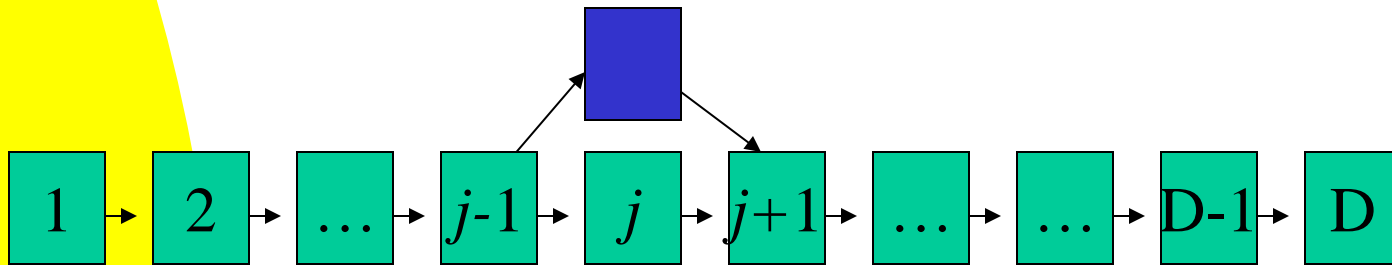
Transform from Dominating Set

- Let $G=(V,E)$, k be instance of DS
- Write $n = |V|$, $c = n^2$, $D = knc + 2n$.
- Take the following tasks and precedences:
- Floor: D tasks in “series”:



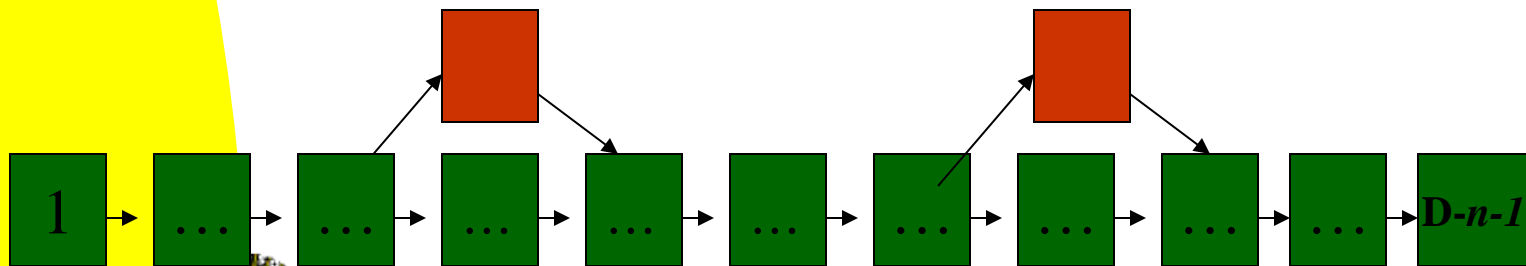
Floor gadgets

- For all j of the form $j = n-1 + ac + bn$ ($0 \leq a < kn$, $1 \leq b \leq n$), take a task that must happen on time j (parallel to the j th floor vertex)



Selector paths

- We take k paths of length $D-n+1$
- Each models a vertex from the dominating set
- To some vertices on the path, we also take parallel vertices:
 - If $\{v_i, v_j\} \notin E$, and $i \neq j$, then place a vertex parallel to the $n-1+ac+in-j^{\text{th}}$ vertex for all a , $0 \leq a < kn$



Lemma and Theorem

- Lemma: we can schedule this set of tasks with deadline D and $2k$ processors, if and only if G has a dominating set of size at most k
- Theorem: Precedence constrained k -processor scheduling is $W[2]$ -hard
- Note: size of instance must depend in polynomial way on size of G (and hence on $k < |V|$)
- It is allowed to use transformations where new parameter is exponential in old parameter



About these hardness proofs

- Fixed parameter proofs: method of showing that a problem *probably* has no FPT-algorithms
- Often complicated proof ☹️
- But not always 😊

4

Kernelisation



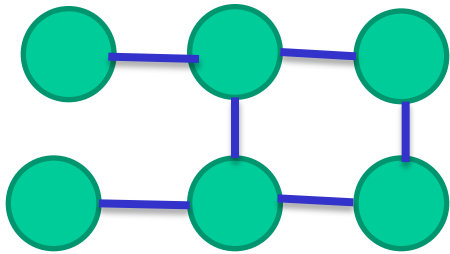
Preprocessing

- Useful technique for solving problems:
 - Preprocess: change instance x to equivalent but smaller instance y
 - Solve the problem on y obtaining solution s'
 - Translate s' back to a solution s for x
- Used very frequently (e.g., CPLEX, sat-solvers, etc. etc.)

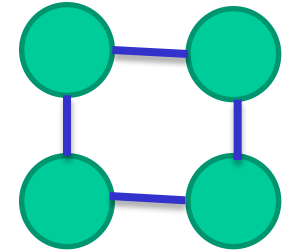
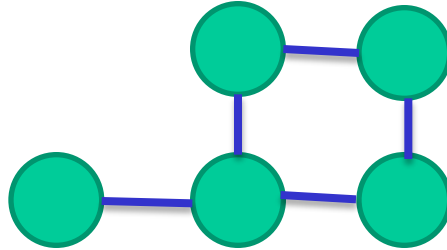
Example 0

- Graph coloring:
 - Given: Graph G , number of colors c
 - Question: can we vertex color G with at most c colors?
- Heuristic preprocessing: remove vertices with at most $c-1$ neighbors, while they exist
- Undoing preprocessing:
 - Suppose we have a coloring of the reduced graph
 - Add the removed vertices back in reverse order. When we add a vertex, it has at most $c-1$ neighbors, so we can color it now.

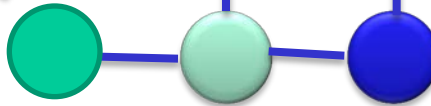
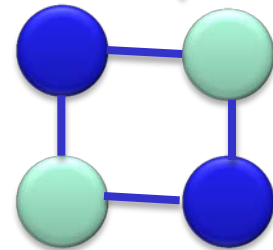




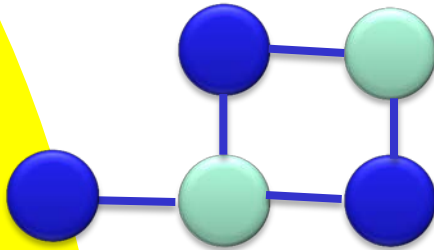
2 colors



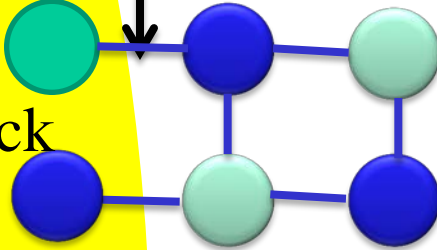
↓ solve



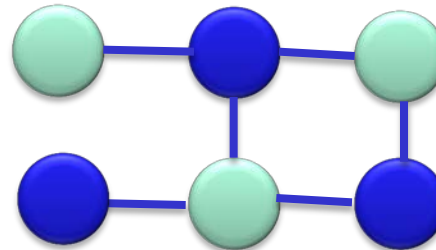
Add back



Color available



Add back



Color available

Done



The area of Kernelization

- Central question: what can we say about the size of a resulting instance?
- What we cannot hope for:
 - An algorithm that always reduces the size of the input to a smaller equivalent one?
 - Why not ... ?

Kernelization

- Preprocessing that is:
 - **Safe**: the answer to the question does not change
 - **Guarantee on size of resulting input as function of a parameter**
 - **Fast** (polynomial time)
- We look at decision problems (answer yes or no)



Kernelization

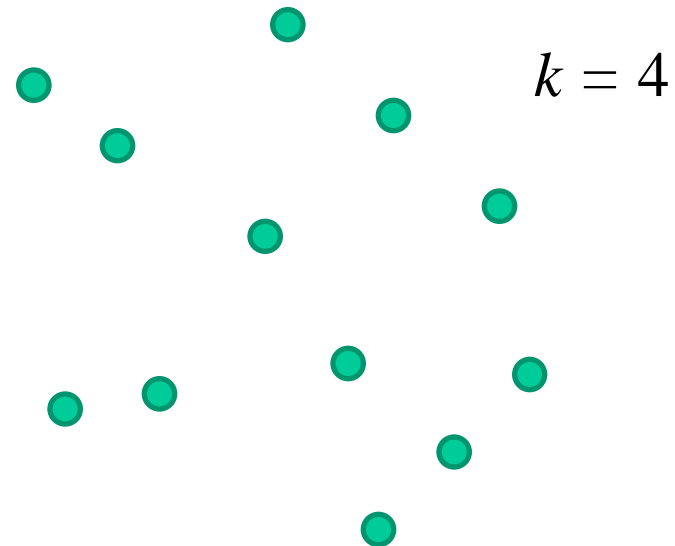
- Preprocessing rules reduce starting instance to one of size $f(k)$
 - Should work in polynomial time
- Then use any algorithm to solve problem on kernel
- Time will be $p(n) + g(f(k))$



Example problem

Point-Line-Cover

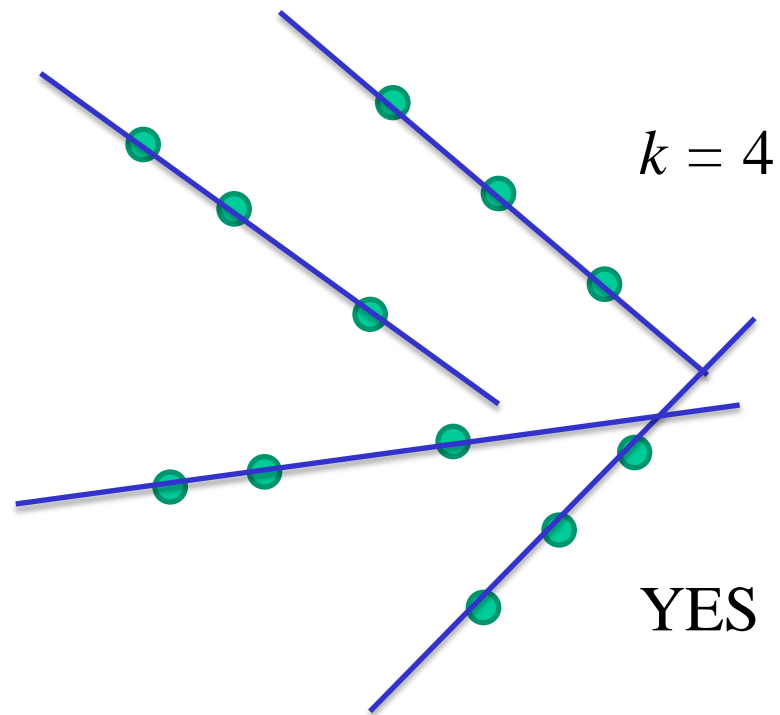
- Given: Set S of points in the plane, integer k
- Parameter: k
- Question: are there k straight lines that hit all the points



Example problem

Point-Line-Cover

- Given: Set S of points in the plane, integer k
- Parameter: k
- Question: are there k straight lines that hit all the points?

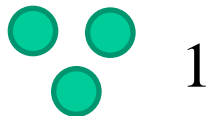


Rule 1

- Observation: if we have a line that hits $k+1$ points, we have to take it
 - Otherwise ...
- **Rule 1:** If we have a line that hits $k+1$ or more points, then
 - Remove the points hit by the line
 - Set $k = k - 1$

Rule 2

- Observation: suppose no line hits more than k points. If we have more than k^2 points, we need more than k lines
- **Rule 2:** If we cannot apply Rule 1, and we have more than k^2 points then say NO
 - Formally: change instance to trivial NO-instance



Kernel for Point-Line-Cover

Algorithm:

- While Rule 1 is possible, apply it
- If Rule 2 is possible, apply it

- Easy: polynomial time
- Trivial: afterwards, we have at most k^2 points



Maximum Satisfiability

- **Given:** Boolean formula in conjunctive normal form; integer k
- **Parameter:** k
- **Question:** Is there a truth assignment that satisfies at least k clauses?
- **Denote:** number of clauses: C

Skip
this
part

Reducing the number of clauses

- If $C \geq 2k$, then answer is YES
 - Look at arbitrary truth assignment, and truth assignment where we flip each value
 - Each clause is satisfied in one of these two assignments
 - So, one assignment satisfies at least half of all clauses

Bounding number of long clauses

- Long clause: has at least k literals
- Short clause: has at most $k-1$ literals
- Let L be number of long clauses
- If $L \geq k$: answer is YES
 - Select in each long clause a literal, whose complement is not yet selected
 - Set these all to true
 - All long clauses are satisfied

Reducing to only short clauses

- If less than k long clauses
 - Make new instance, with only the short clauses and k set to $k-L$
 - There is a truth assignment that satisfies at least $k-L$ short clauses, if and only if there is a truth assignment that satisfies at least k clauses
 - \Rightarrow : choose for each satisfied short clause a variable that makes the clause true. We may change all other variables, and can choose for each long clause another variable that makes it true
 - \Leftarrow : trivial

An $O(k^2)$ kernel for Maximum Satisfiability

- If at least $2k$ clauses: return YES
- If at least k long clauses: return YES
- Else: remove all L long clauses, and set $k=k-L$



Formal definition of kernelisation

- Let P be a parameterized problem. (Each input of the form (I, k) .) A *reduction to a problem kernel* is an algorithm, that transforms A inputs of P to inputs of P , such that
 - $P((I, k))$, if and only if $P(A(I, k))$ for all (I, k)
 - If $A(I, k) = (I', k')$, then $k' \leq f(k)$, and $|I'| \leq g(k)$ for some functions f, g
 - A uses time, polynomial in $|I|$ and k

A theorem with a strange proof

- **Theorem (folklore):** Let Q be a decidable parameterized problem. The following are equivalent:
 1. Q belongs to FPT, i.e., has an algorithm with time $O(f(k)n^c)$ for fixed c
 2. Q has a (reduction to a problem) kernel

Proof part 1

- Suppose Q has a kernel. Then this is an FPT algorithm:
 - Given: instance x , parameter k
 - Build the kernel y, k' (has size $f(k)$)
 - Run any algorithm to decide on y, k'
- Running time is $p(|x|) + g(f(k))$ for polynomial p and some function g
 - $p(|x|)$ for making kernel
 - $g(f(k))$ for solving kernel



Proof part 2

- ☹️
- If P is in FPT, P has a (perhaps trivial) reduction to a problem kernel
 - Given: instance x , parameter k
 - Suppose we have an $f(k) n^c$ algorithm
 - If $|x| > f(k)$, solve problem exactly: this is $O(n^{c+1})$ time
 - Formality: take small yes or no-instance afterwards
 - Otherwise, output x, k (i.e., do nothing)
 - We have that $|x| \leq f(k)$.

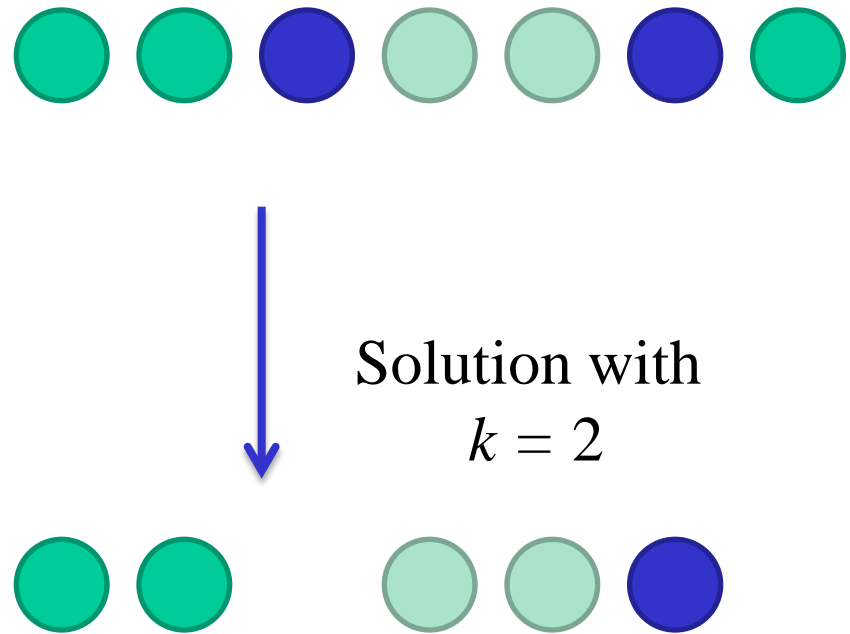
Implications of the theorem

- Positive:
 - Technique to obtain FPT-algorithms:
 - Make small kernel.
 - Algorithm on resulting small instance.
- Negative:
 - If we have evidence that there exists no FPT-algorithm, we also have evidence that there exists no kernel.



Another kernel example

- Convex colored marbles
 - Real application in computational biology
 - Given: sequence of colored marbles, integer k
 - Parameter: k
 - Question: can we remove at most k marbles such that for each color, all marbles with that color are consecutive?

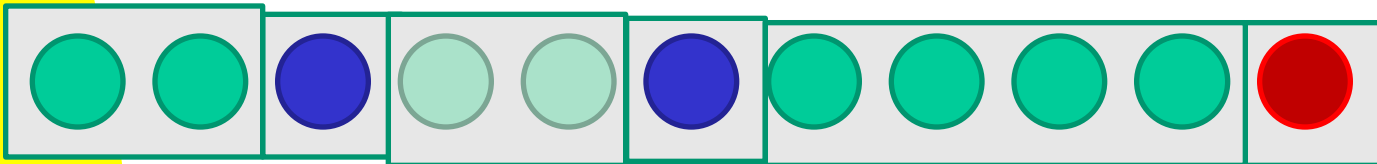


Algorithm scheme

- Some safe rules:
 - Do not change answer to the problem
 - Simplify the instance
- Apply the rules while possible
- Argument that resulting instance has bounded size
- Plan: build rules that limit some aspect of the input

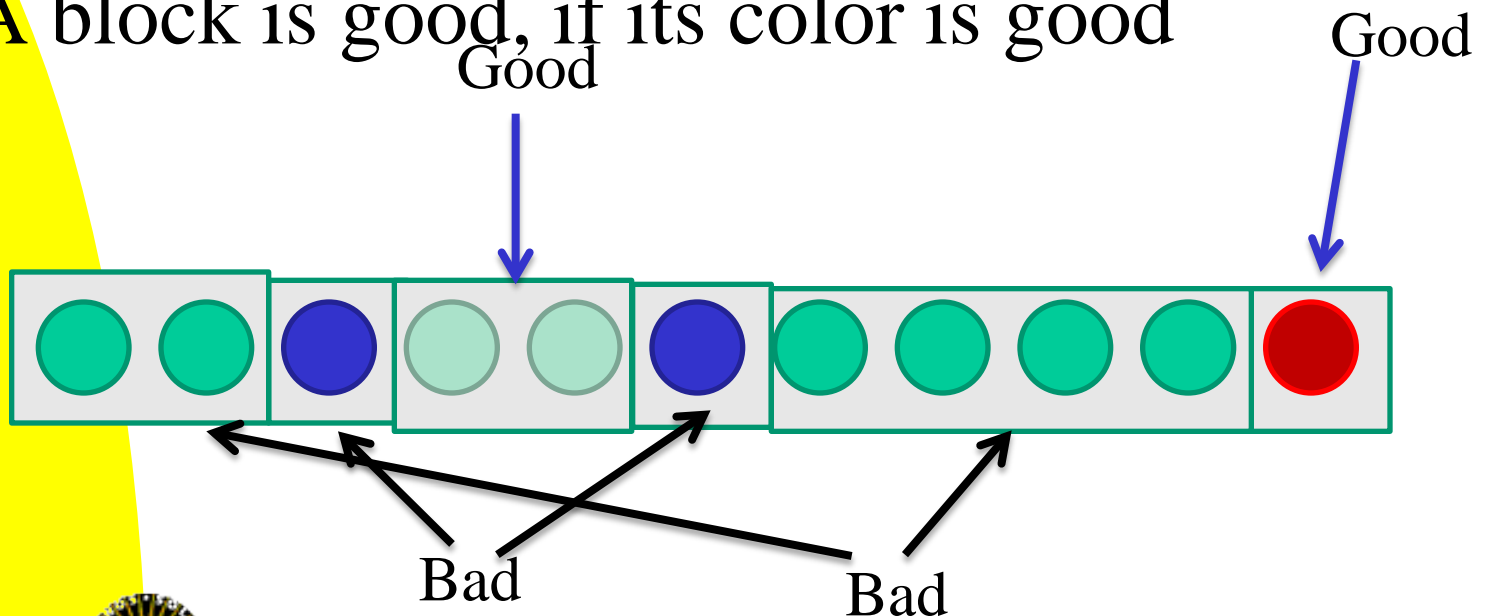
Blocks

- A block is a maximum consecutive part of similarly colored marbles



Good colors and bad colors

- A color is *good*, if there is only one block with this color, otherwise it is bad
- A block is good, if its color is good

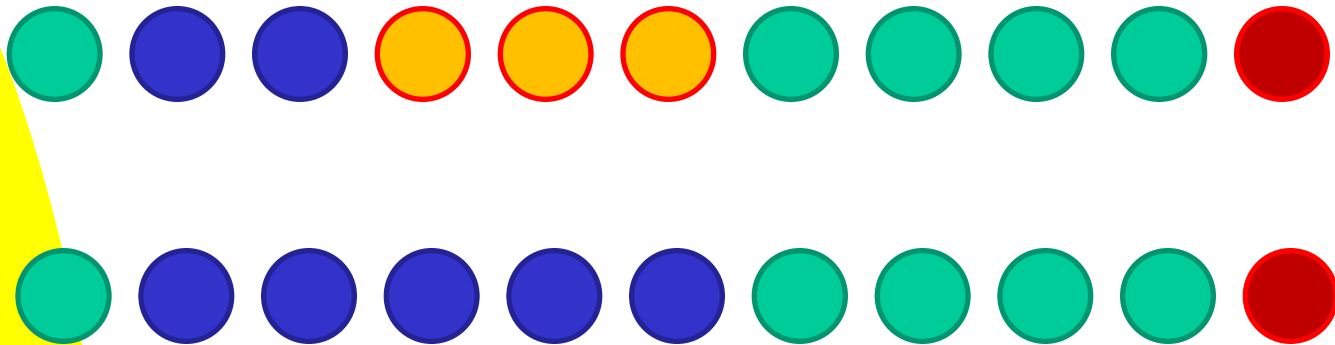


Reducing number of blocks of bad colors

- Observation: each removal can reduce the number of bad blocks by at most 4
 - The removed marble
 - The two neighboring blocks could become one
- Rule 1: If there are more than $4k$ blocks with a bad color, say NO

Rule 2

- If we have two consecutive good blocks, give them the same color



Counting

- We have at most $4k$ bad blocks, and each good block is between bad blocks: at most $4k+1$ good blocks, and at most $8k+1$ blocks
- We need some way to bound the size of blocks ...



Bounding the size of blocks

- Rule 3: If a block has more than $k+1$ marbles, change its size to $k+1$
 - Why correct?
- Resulting algorithm:
 - Apply rules while possible
- Kernel size: at most $(8k+1)(k+1)$ marbles



Many small kernels exist

- Graph problems: Feedback vertex set, vertex cover, many problems on planar graphs, ...
- Logic: can we satisfy at least k clauses of a Satisfiability instance in CNF, ...
- ...

Negative results

- Recall:

Theorem If $W[1] = \text{FPT}$, then the *Exponential Time Hypothesis* is not valid.

Corollary A parameterized problem that is $W[1]$ -hard has no kernel, unless the ETH does not hold.

Many $W[1]$ -hard problems

- Many problems are $W[1]$ -hard, e.g.: Clique, Independent Set, Dominating Set, ...
- No kernels for these, unless $W[1] = FPT$ and hence the Exponential Time Hypothesis fails.

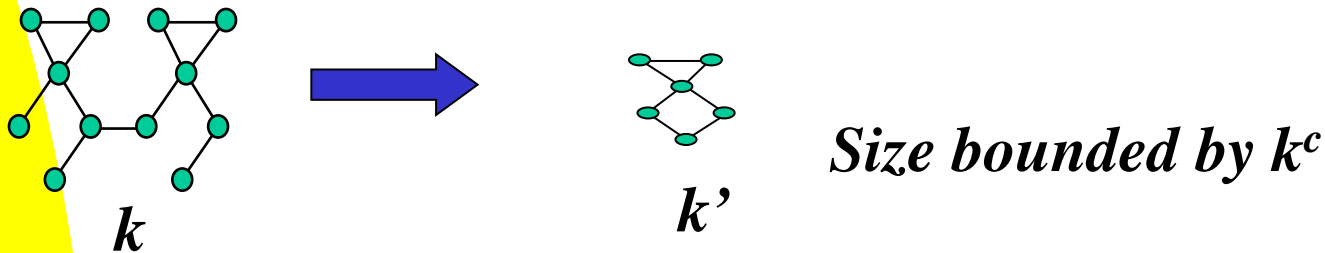


Problems with large kernels

- For many problems in FPT, we do not know small kernels.
- Consider:
 - Long Path**
 - **Given:** Graph $G=(V,E)$, integer k .
 - **Question:** Does G have a simple path of length at least k ?
 - **Parameter:** k .
- Is in FPT, but all known kernels have size exponential in k ...

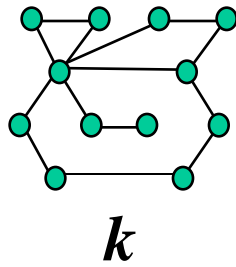
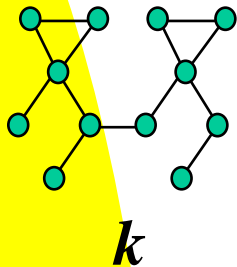
Does Long Path have a kernel of polynomial size? Maybe not...

- Suppose we have a polynomial kernel, say with k^c bits size.

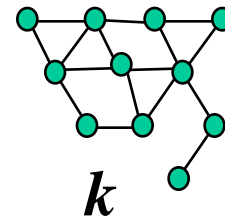


Long path continued

- Now, suppose we have a series of inputs to long path, say all with the same parameter: (G_1, k) , (G_2, k) , \dots , (G_r, k) .

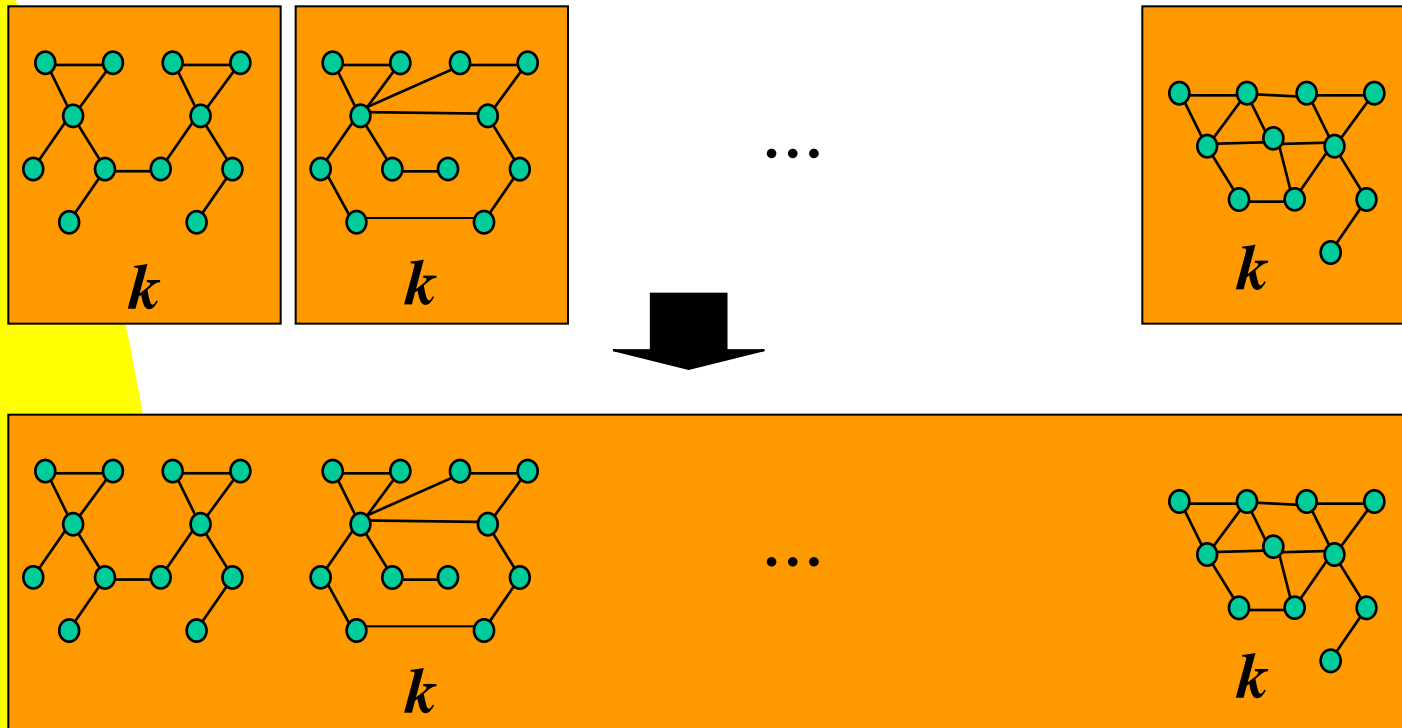


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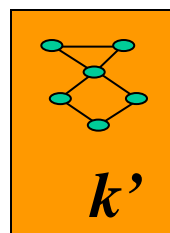
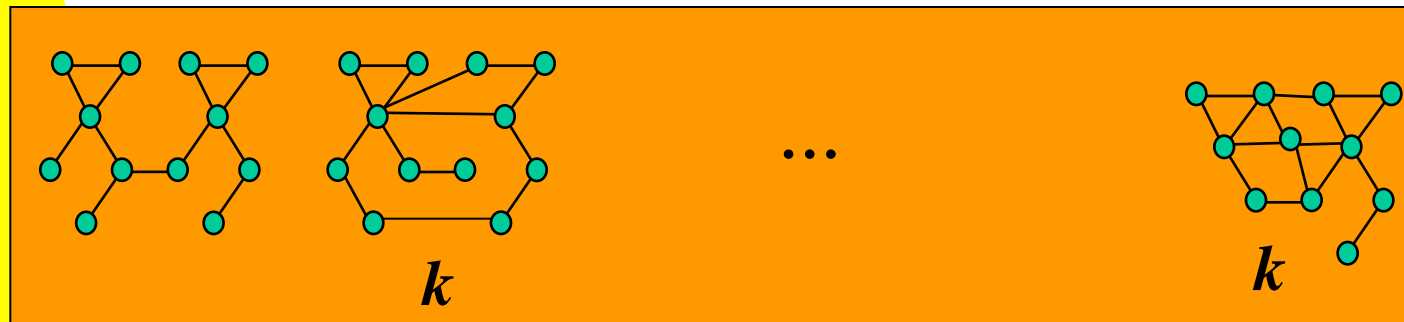
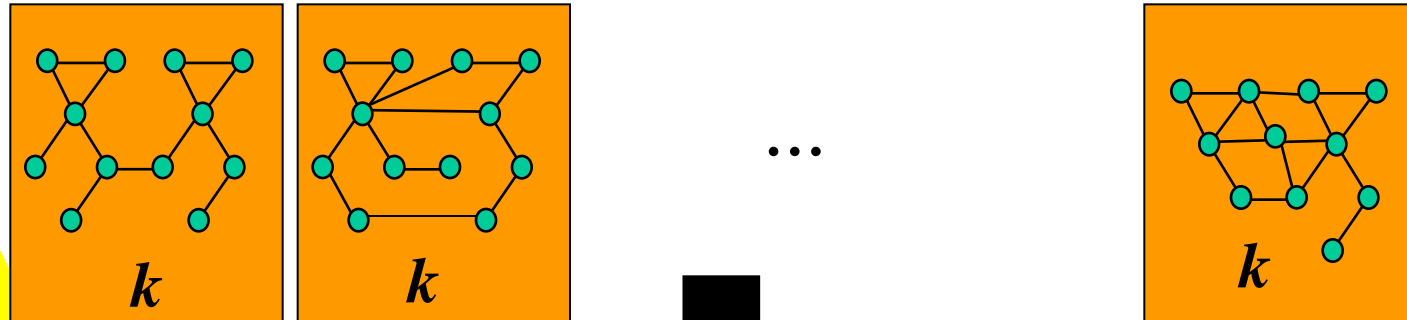


Take the disjoint union

- $G_1 \cup G_2 \cup \dots \cup G_r$ has a simple path of length k , if and only if there exists a graph G_i that has a path of length k .



And now, apply the kernel to the union



Size bounded by k^c

What happened?

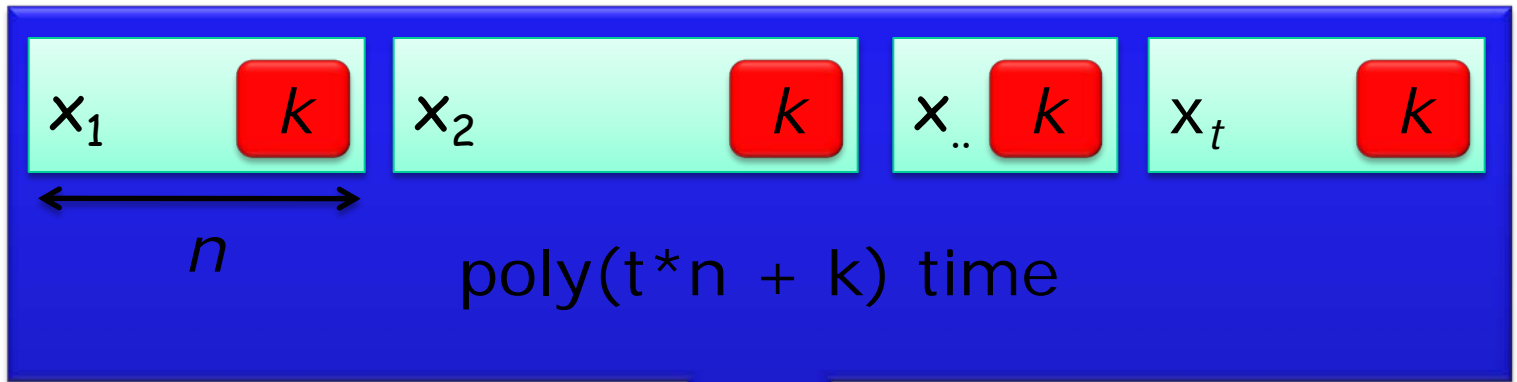
- We have **many** (say $r = k^{2c}$) instances of Long Path, and transform it to **one** instance of **size** $< k^c$.
- *Intuition*: this cannot be possible without solving some of the instances, as we have **fewer bits left** than we had **instances to start with**...
- Theory (next) formalizes this idea.

(Or-)Compositionality

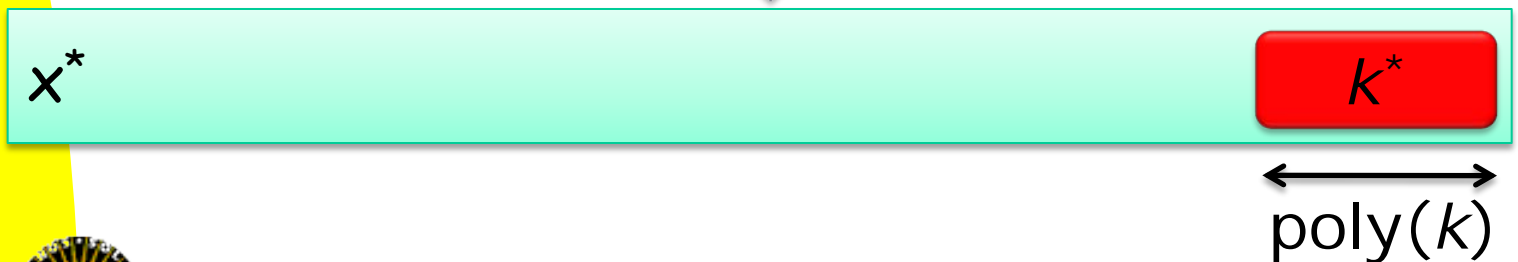
- A parameterized problem Q is *or-compositional*, if there is an algorithm that
 - Receives as **input a series of inputs** to Q , all with the same parameter $(I_1, k), \dots, (I_r, k)$;
 - Uses polynomial time;
 - **Outputs one input** (I', k') to Q ;
 - k' bounded by polynomial in k ;
 - $(I', k') \in Q$ if and only if **there exists at least one** j with $(I_j, k) \in Q$.

Or-composition

Q
instances



Q
instance



Compositionality gives lowerbounds for kernels

Theorem (B, Downey, Fellows, Hermelin + Fortnow, Santhanam, 2008)

Let P be a parameterized problem that is

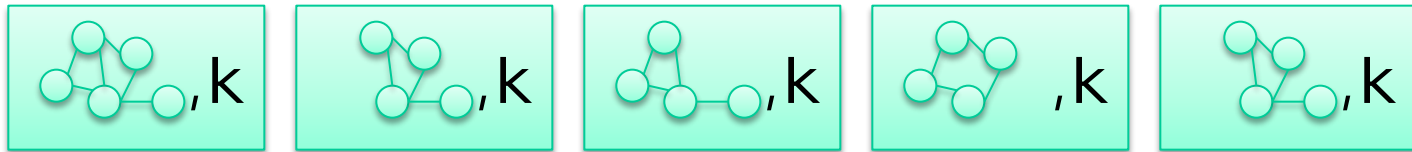
- **Or-compositional**, and
- “Unparameterized form” is **NP-complete**.

Then P has no polynomial kernel unless $\text{NP} \subseteq \text{coNP/poly}$.

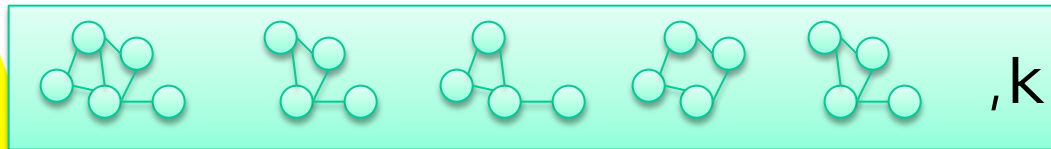
- Variant for and-compositionality also exists, with recent (2012) result by Drucker

Application to Long Path

- **Input:** t instances of Longest Path.



- Take disjoint union, output as (G', k) .



- G' has a path of length $k \Leftrightarrow$ some G_i has a path of length k .
- Output parameter trivially bounded in $\text{poly}(k)$.

Long Path does not admit a polynomial kernel unless $\text{NP} \subseteq \text{coNP}/\text{poly}$

Additional techniques (1)

- **Polynomial parameter transformations** (several authors): transform an argument that problem X does not have a polynomial kernel to an argument that problem Y does not have a polynomial kernel.
- Chen et al. (2009): no kernels of size $k^c n^{1-\varepsilon}$ (unless $NP \subseteq coNP/poly$).
- **Cross-compositions** (B, Jansen, Kratsch, 2010): (composition of instances of problem X into instances of problem Y).
 - Composition of 2^n instances suffices.



Additional techniques (2)

- Dell and van Melkebeek (2010): extend technique to **precise lower bounds**, e.g.: $\Omega(k^2)$ bits for kernel for Vertex Cover (unless $\text{NP} \subseteq \text{coNP}/\text{poly}$).
- E.g.: Kratsch (2013, unpublished): there is no kernel for Point-Line-Cover with $O(k^{2-\varepsilon})$ points unless $\text{NP} \subseteq \text{coNP}/\text{poly}$ for $\varepsilon > 0$.
- ...

Disjoint cycles

- **Disjoint cycles**
 - **Given:** Graph $G=(V,E)$, integer k .
 - **Question:** Does G contain k vertex disjoint cycles?
 - **Parameter:** k .
- NP-complete, FPT, but does it has a polynomial kernel??
- Resembles Feedback Vertex Set, but behaves differently!
 - **Feedback vertex set**
 - **Given:** Graph G , integer k .
 - **Question:** Is there a set of k vertices W such that $G-W$ has no cycle?
 - **Parameter:** k .
 - FVS has $O(k^2)$ kernel (Thomassé)



PPT-transformation

- A **polynomial-parameter-time transformation** (ppt-transformation) P to Q is an algorithm
 - which takes an instance (x, k) of P as input,
 - uses time polynomial in $|x| + k$,
 - outputs an instance (x', k') of Q with
 - $(x, k) \in P \Leftrightarrow (x', k') \in Q$,
 - k' is polynomial in k .

Theorem: If P has a ppt-transformation to Q , Q is NP-complete, P is in NP, and P has no polynomial kernel, then Q has no polynomial kernel.

Proof

Theorem: If P has a ppt-transformation to Q, Q is NP-complete, P is in NP, and P has no polynomial kernel, then Q has no polynomial kernel.

Proof Suppose Q has a polynomial kernel. Build a polynomial kernel for P as follows:

- Take input (x,k) for P.
- Transform (x,k) to input (y,l) for Q with **ppt-transformation**.
- Use **kernel** on (y,l) : gives equivalent (y',l') for Q with polynomial size bound on $|y|$.
- **NP-completeness gives transformation** from Q to P: apply it to (y',l') gives equivalent (x',k') with $|x'|$ polynomially bounded in $|y'|+l'$, which is **polynomially bounded in (x,k)** . ■



Intermediate problem: Disjoint Factors

- **Disjoint Factors**
 - **Given:** Integer k , string s on alphabet $\{1, 2, \dots, k\}$.
 - **Question:** Can we find disjoint substrings s_1, s_2, \dots, s_k in s such that s_i starts and ends with i ?
 - **Parameter:** k
- Disjoint Factors is NP-complete.
- Solvable with Dynamic Programming in $2^k / |s|$ time.
- Next: compositionality.

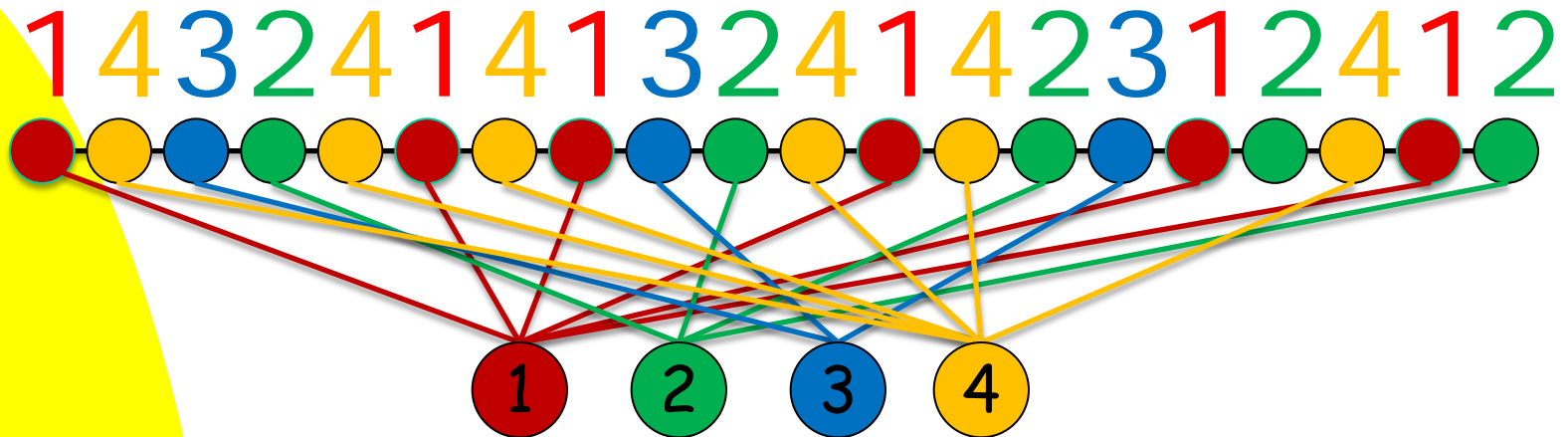
1 4 3 2 4 1 4 1 3 2 4 1 4 2 3 1 2 4 1 2

Disjoint Factors is compositional: proof by example

- Number of instances r can be bounded by 2^k otherwise we can solve them all in polynomial time.
- Take $\log r$ new characters, and build new string, like (example for $r=4$):
 - **b a s_1 a s_2 a b a s_3 a s_4 a b**
 - New characters “eat” all but one instance, in which we must then find the other factors:
 - **b a s_1 a s_2 a b** a s_3 a s_3 a b

Corollary: Disjoint Factors has no polynomial kernel unless $\text{NP} \subseteq \text{coNP}/\text{poly}$.

PPT-transformation from Disjoint Factors to Disjoint Cycles



Disjoint Cycles does not admit
a polynomial kernel unless
 $NP \subseteq coNP/poly$

Overview of problem behavior

- **$O(1)$ size kernels:** problems in P. Ex: Eulerian Graph
⇕ NP-completeness (variable parameter)
- **Polynomial kernels** Shown with algorithm. Ex.: Vertex Cover
⇕ compositionality, ppt-transformations, cross-composition
- **Kernels, but not polynomial sized.** Shown (usually) with FPT-algorithm. Ex: Long Path
⇕ W[1]-hardness
- **XP:** No kernel, polynomial if parameter is bounded. Ex.: Independent Set
⇕ NP-completeness (fixed parameter)
- **Bad.** Example: Graph Coloring is NP-complete for 3 colors

6

Conclusions



Conclusions

- Fixed parameter tractability
 - Tells how to distinguish between $O(f(k)n^c)$ and $O(n^{f(k)})$
 - Practical (and theoretical) algorithms
- Kernelization
 - Analysis of preprocessing
 - Relation with ftp
- Question to you:
 - Do these notions have relevance to your work?

